# Mimas Scatterometry Rev 064

R. West, C. Veeramachaneni April 1, 2009

• Sequence: s39

• Rev: 064

• Observation Id: mi\_064\_1

• Target Body: Mimas

### 1 Introduction

This memo describes one of the Cassini RADAR activities for the s39 sequence of the Saturn Tour. This activity is a distant scatterometer/radiometer observation of Mimas. A sequence design memo provides the science context of the scheduled observations, an overview of the pointing design, and guidelines for preparing the RADAR IEB. A 3-hour warmup occurs first using the parameters shown in table 4.

## 2 CIMS and Division Summary

CIMS ID	Start	End	Duration	Comments
064MI_SCATTRAD001_PRIME	2008-102T09:20:00	2008-102T11:20:00	02:00:0.0	Point -Z axis at
				target and execute
				raster scan(s) cen-
				tered on target.
				Obtain simultaneous
				scatterometry and
				radiometry.

Table 1: mi\_064\_1 CIMS Request Sequence

Each RADAR observation is represented to the project by a set of requests in the Cassini Information Management System (CIMS). The CIMS database contains requests for pointing control, time, and data volume. The CIMS requests show a high-level view of the sequence design.

The CIMS requests form the basis of a pointing design built using the project pointing design tool (PDT). The details of the pointing design are shown by the PDT plots on the corresponding tour sequence web page. (See https://cassini.jpl.nasa.gov/radar.) The RADAR pointing sequence is ultimately combined with pointing sequences from other instruments to make a large merged c-kernel. C-kernels are files containing spacecraft attitude data.

A RADAR tool called RADAR Mapping and Sequencing Software (RMSS) reads the merged c-kernel along with other navigation data files, and uses these data to produce a set of instructions for the RADAR observation. The

Division	Name	Start	Duration	Data Vol	Comments
a	distant_radiometer	0.00:00:00	00:20:0.0	1.2	radiometer
b	distant_radiometer	00:20:0.0	00:05:0.0	0.3	On-target radiometer
С	distant_scatterometer	00:25:0.0	00:15:0.0	216.0	Scatterometer target-center
					stare with tone
d	scat_compressed	00:40:0.0	00:05:0.0	1.3	On-target scatt compressed
					9 dB calibration
e	distant_radiometer	00:45:0.0	01:00:0.0	3.6	radiometer filler and raster
f	scat_compressed	01:45:0.0	00:05:0.0	1.3	Off-target scatt com-
					pressed 9 dB calibration
g	distant_radiometer	01:50:0.0	00:05:0.0	0.3	Closing radiometry
Total				223.9	

Table 2: Division summary. Data volumes (Mbits) are estimated from maximum data rate and division duration.

Div	Alt (km)	Slant range (km)	B3 Size (target dia)	B3 Dop. Spread (Hz)
a	106926	off target	1.74	off target
b	107297	107297	1.74	6343
С	108029	108029	1.76	6225
d	111633	111633	1.81	5740
e	113266	113267	1.84	5546
f	144362	off target	2.35	off target
g	147553	off target	2.40	off target

Table 3: Division geometry summary. Values are computed at the start of each division. B3 Doppler spread is for two-way 3-dB pattern. B3 size is the one-way 3-dB beamwidth

Name	Nominal	Actual	Mismatch	Comments
mode	radiometer	radiometer	no	Comments
start_time (min)	varies	0.0	no	
end_time (min)	varies	20.0	no	
time_step (s)	varies	1800.0	no	Used by radiome-
time_step (s)	varies	1800.0	110	•
	00100	00100		ter only modes
bem	00100	00100	no	
baq	don't care	5	no	
csr	6	6	no	
noise_bit_setting	don't care	4.0	no	
dutycycle	don't care	0.38	no	
prf (Hz)	don't care	1000	no	
tro	don't care	0	no	
number_of_pulses	don't care	8	no	
n_bursts_in_flight	don't care	1	no	
percent_of_BW	don't care	100.0	no	
auto_rad	on	on	no	
rip (ms)	34.0	34.0	no	starting value for
				auto-rad
max_data_rate	0.992	0.992	no	1 Kbps - 1 s burst
				period which is
				adequate for slow
				radiometer scans
interleave_flag	off	off	no	
interleave_duration (min)	don't care	10.0	no	

Table 4: mi\_064\_1 Div a distant\_radiometer block

Name	Nominal	d	f	Mismatch	Comments
mode	scat_compressed	scat_compressed	scat_compressed	yes	
start_time (min)	varies	40.0	105.0	no	
end_time (min)	varies	45.0	110.0	no	
time_step (s)	don't care	24.0	24.0	no	Set by valid time calculation
bem	00100	00100	00100	no	
baq	3	3	3	no	3 - PRI summation
CST	1	1	1	no	1 - receive only antenna measure- ment
noise_bit_setting	4.0	4.0	4.0	no	9 dB setting used by all low SNR scatterometry
dutycycle	don't care	0.38	0.38	no	
prf (Hz)	1200	1200	1200	no	
tro	don't care	6	6	no	automatically set to 6
number_of_pulses	150	150	150	no	Set with the PRF to fill the science data buffer - Only 2 PRI's worth of data are downlinked.
n_bursts_in_flight	1	1	1	no	
percent_of_BW	don't care	0.0	0.0	no	
auto_rad	on	on	on	no	
rip (ms)	34.0	34.0	34.0	no	
max_data_rate	4.300	4.300	4.300	no	
interleave_flag	off	off	off	no	
interleave_duration (min)	don't care	10.0	10.0	no	

Table 5: mi\_064\_1 Div df scat\_compressed block

RADAR instructions are called an Instrument Execution Block (IEB). The IEB is produced by running RMSS with a radar config file that controls the process of generating IEB instructions for different segments of time. These segments of time are called divisions with a particular behavior defined by a set of division keywords in the config file. Table 2 shows a summary of the divisions used in this observation. Subsequent sections will show and discuss the keyword selections made for each division. Each division table shows a set of nominal parameters that are determined by the operating mode (eg., distant scatterometry, SAR low-res inbound). The actual division parameters from the config file are also shown, and any meaningful mismatches are flagged.

## 3 Receive Only Engineering Test Measurements

Div D and F (see table 5) provide scatt mode, 9 dB attenuator receive only data on and off target for calibration of the scatterometer tone integration data. All of the receive only data is collected in compressed mode to get more integration time. The PRF and number of pulses are chosen to fill the science data buffer. These parameters give the best performance possible from the compressed mode.

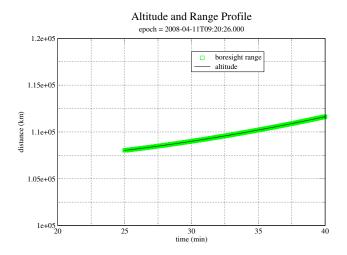


Figure 1: Div C: Altitude and range to the boresight point

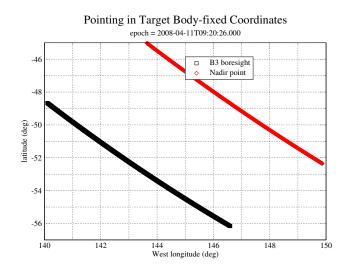


Figure 2: Div C : Stare in target body-fixed coordinates

## 4 Div C: Mimas Scatterometry

Figures 1 and 2 show the pointing design for the scatterometry stare from the merged ckernel. The angular size of the target is about 3.5 mrad during this division. The beam 3 beamwidth is 6 mrad. The division parameters for the tone target integration divisions are shown in table 6.

#### 4.1 Scatterometer Performance

The detection performance is shown in figures 3, 4, and 5. The maximum doppler spread in Div c is 6225 Hz which comes from rotation and spacecraft motion. Normally the PRF needs to be higher than the doppler spread to support potential range-doppler processing, and is set by division parameter to 781 Hz. With this PRF, the range amiguity spacing is 192 km while Mimas is 199 km in radius. The range-spread of the beam depends on where it is pointed. For target centered pointing the cosine law can be applied to solve the geometry. At 108029 km range, the range-spread is 198 km. A PRF setting higher that the doppler spread was not possible in this case, and the low PRF setting used will not allow range/doppler processing. Fig. 4 shows that disk integrated results should be reasonably stable.

Name	Nominal	Actual	Mismatch	Comments
mode	scatterometer	scatterometer	no	
start_time (min)	varies	25.0	no	
end_time (min)	varies	40.0	no	
time_step (s)	don't care	24.0	no	Used when BIF >
				1, otherwise set
				by valid time cal-
				culation
bem	00100	00100	no	
baq	5	5	no	
csr	0	0	no	0 - normal op-
				eration with
				fixed attenuator
				set to match
				Phoebe for easier
				cross-calibration
noise_bit_setting	4.0	4.0	no	Scat signal set
				higher than
				ALT/SAR
dutycycle	0.70	0.60	yes	
prf (Hz)	varies	781	no	Set to cover
				doppler spread
				and to allow CSF
				= integer multiple
tro	6	6	no	6 - allows for
				some noise only
				data in time do-
				main
number_of_pulses	varies	54	no	depends on PRF
				choice (can have
				more shorter
				pulses)
n_bursts_in_flight	varies	2	no	Used to increase
				PRF and data rate
				at long range
percent_of_BW	0.0	0.0	no	
auto_rad	on	on	no	
rip (ms)	34.0	34.0	no	
max_data_rate	200.000	240.000	yes	Kbps - determines
				burst period
interleave_flag	off	off	no	
interleave_duration (min)	don't care	10.0	no	

Table 6: mi\_064\_1 Div c distant\_scatterometer block

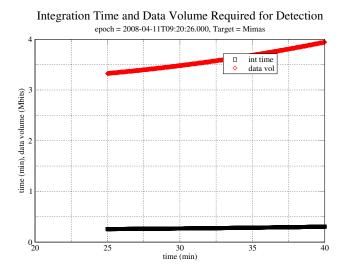


Figure 3: Scatterometry Div C: Detection integration time required for a single point detection using optimal chirp bandwidth

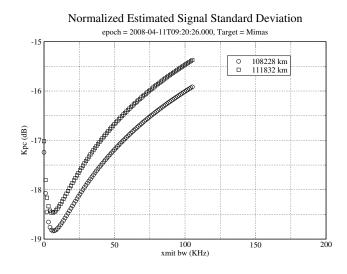


Figure 4: Div C: Normalized estimated signal standard deviation for a disk integrated observation using optimal chirp bandwidth and assuming all the bursts occur at minimum range, and 15 minutes away from minimum range.

#### Multi-look Normalized Estimated Signal Standard Deviation

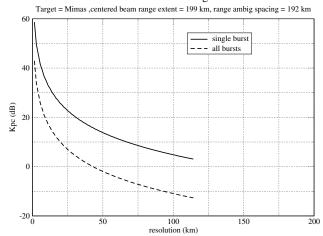


Figure 5: Div C: Normalized estimated signal standard deviation for a range/doppler cell as a function of resolution. Range/doppler resolution elements are both set equal to the specified resolution. Results are shown for a single burst, and for all the bursts in this division. Calculations are performed using the geometry at the start of the division. The presence of ambiguities are not shown.

#### 5 **Revision History**

1. March 31, 2009: Initial Release

# **Acronym List**

ALT	Altimeter - one of the radar operating modes
BAQ	Block Adaptive Quantizer
CIMS	Cassini Information Management System - a database of observations
Ckernel	NAIF kernel file containing attitude data
DLAP	Desired Look Angle Profile - spacecraft pointing profile designed for optimal SAR performance
ESS	Energy Storage System - capacitor bank used by RADAR to store transmit energy
IEB	Instrument Execution Block - instructions for the instrument
ISS	Imaging Science Subsystem
IVD	Inertial Vector Description - attitude vector data
IVP	Inertial Vector Propagator - spacecraft software, part of attitude control system
INMS	Inertial Neutral Mass Spectrometer - one of the instruments
NAIF	Navigation and Ancillary Information Facility
ORS	Optical Remote Sensing instruments
PDT	Pointing Design Tool
PRI	Pulse Repetition Interval
PRF	Pulse Repetition Frequency
RMSS	Radar Mapping Sequencing Software - produces radar IEB's
SAR	Synthetic Aperture Radar - radar imaging mode
SNR	Signal to Noise Ratio
SOP	Science Operations Plan - detailed sequence design
SOPUD	Science Operations Plan Update - phase of sequencing when SOP is updated prior to actual sequencing
SSG	SubSequence Generation - spacecraft/instrument commands are produced
SPICE	Spacecraft, Instrument, C-kernel handling software - supplied by NAIF to use NAIF kernel files.
TRO	Transmit Receive Offset - round trip delay time in units of PRI